

# Math 307 Lecture 17

## Forced Vibrations

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University of Washington

May 14, 2014

# Today!

## Last time:

- More on Mechanical and Electrical Vibrations

## This time:

- Forced vibrations

## Next time:

- Review for final exam

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# Outline

- 1 **Forced Vibrations Introduction**
  - First Examples
  - Alternating Current and LCR Circuits
- 2 **Forced Vibration Example**
  - LCR Circuit Specific Example
  - DC Case
  - AC Case



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# What is Forced Vibration?

- Forced vibration is what occurs when we have an equation of the form

$$ay'' + by' + cy = R \cos(\omega t).$$

- where  $a, b, c$  are positive constants
- Intuitively, we should think about a spring with an external periodic force applied.
- What solutions look like depend very strongly on the values of  $a, b, c, R$ , and  $\omega$
- Today we will look at behavior when  $b > 0$
- Later we will study separately the case when  $b = 0$

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# Examples of Forced Vibration

- Forced vibrations occur naturally all the time!
- For example one could think of
  - A mass-spring system, with an external force applied
  - A LCR-circuit, where the voltage input  $E(t)$  is not constant
- What does forced vibration look like in comparison to unforced vibration?
- How does forced vibration behave at large timescales?

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## LCR-circuit example

- Last class, we found that the current in an LCR-circuit with inductance  $L$ , capacitance  $C$ , and resistance  $R$  (all positive constants) satisfies the second-order equation

$$LI'' + RI' + I/C = E'(t)$$

- where here  $E(t)$  is the voltage input into the LCR circuit by some power source
- power source could be a battery, or similar device
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- Suppose that our voltage source is  $V_0$  volts
- Depending on the kind of source, this may mean two different things
- If the source is a battery, then the voltage is *direct* and  $E(t) = V_0$ , so that  $E'(t) = 0$
- If the source is a wall outlet or alternator, the voltage is *alternating*
- In this case  $V_0$  typically refers to the *rms voltage*, so that the true voltage input is  $E(t) = \sqrt{2}V_0 \sin(\omega t)$ , where  $\omega$  is the electrical angular frequency of the power source
- For wall outlets in the U.S.A.,  $\omega/2\pi = 60$  Hz

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# LCR-circuit: direct current case

- Suppose that our voltage source is  $V_0$  volts in direct current (ie. from a battery or DC generator)
- Then  $E(t)$  is constant, so  $E'(t) = 0$
- Also assume that  $R > 0$  (which is *always* true in real life)
- The current satisfies the equation

$$LI'' + RI' + I/C = 0$$

- and for  $R^2 < 4L/C$ , the solution is of the form

$$I = re^{-Rt/2L} \cos(\mu t - \delta)$$

- where  $\mu = (\sqrt{R^2 - 4L/C})/2L$ , and  $r, \delta$  are constants depending on the initial conditions  $I(0)$  and  $I'(0)$

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- How does  $I(t)$  behave at large time?
- It becomes very small, approaching zero exponentially fast
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# LCR-circuit: alternating current case

- Suppose that our voltage source is  $V_0$  volts in alternating current (ie. from a wall socket or alternator)
- Then  $E(t) = \sqrt{2} V_0 \sin(\omega t)$ , so  $E'(t) = \sqrt{2} \omega V_0 \cos(\omega t)$
- Also assume that  $R > 0$  (which is *always* true in real life)
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- In this case, the solution has two components

$$I = \underbrace{c_1 l_1 + c_2 l_2}_{\text{solution to homogeneous equation}} + \underbrace{l_p}_{\text{particular solution}}$$

- Where  $c_1, c_2$  are constants, depending on initial condition

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## LCR-circuit: alternating current case

- As the solution to the homogeneous equation we derived before shows us, the solution to the homogeneous equation will become very small at large times
- Therefore, at large times, the general solution will look very similar to the particular solution
- For this reason, we often call  $c_1 I_1 + c_2 I_2$  the *transient solution* (in the case of circuits, also called a transient current)
- And we call  $I_p$  the *steady state solution* or *forced response* (in the circuit case, also called *steady state current*).



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- For this reason, we often call  $c_1 I_1 + c_2 I_2$  the *transient solution* (in the case of circuits, also called a transient current)
- And we call  $I_p$  the *steady state solution* or *forced response* (in the circuit case, also called *steady state current*).

## LCR-circuit: alternating current case

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- Thus we write

$$I = I_{\text{transient}} + I_{\text{steady}},$$

- where  $I_{\text{steady}}$  is a particular solution of

$$LI'' + RI' + I/C = \sqrt{2}\omega V_0 \cos(\omega t)$$

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- Straightforward but tedious algebraic calculation may be used to show

$$I_{\text{steady}} = r \cos(\omega t - \delta),$$

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  - First Examples
  - Alternating Current and LCR Circuits
- 2 **Forced Vibration Example**
  - **LCR Circuit Specific Example**
  - DC Case
  - AC Case

## LCR-circuit example

### Example

Suppose that an LCR-circuit has a 1 H inductor, a 1 F capacitor, and a  $0.125\Omega$  resistor. Also suppose that the initially  $I'(0) = 0$  and  $I(0) = 2$ . If a voltage source of 0.25 volts is connected, determine the current as a function of time.

We consider two cases:

- when the voltage source is direct current (DC)
- when the voltage source is alternating current (AC)



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# LCR-circuit example: DC case

- Assume that the voltage source is direct
- We have that  $C = 1$ ,  $L = 1$ , and  $R = 0.125$ .
- In this case,  $E(t) = 0.25$ ,  $E'(0) = 0$ , so that  $I$  is a solution to the initial value problem

$$I'' + 0.125I' + I = 0, \quad I(0) = 2, \quad I'(0) = 0$$

- We solved this last time, and got

$$I = \frac{32}{\sqrt{255}} e^{-t/16} \cos\left(\frac{\sqrt{255}}{16}t - \delta\right)$$

$$\text{for } \delta = \tan^{-1} \frac{1}{\sqrt{255}} \approx 0.0625$$

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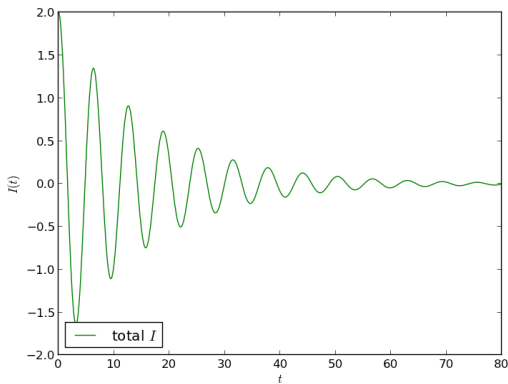
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Figure : Current in the LCR circuit  $L = 1$ ,  $C = 1$ ,  $R = 0.125$ ,  $E = 0.25$ , with the initial condition  $I(0) = 2$  and  $I'(0) = 0$



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# LCR-circuit example: AC case

- Assume the voltage source is alternating with angular frequency  $\omega = 1$
- We have that  $C = 1$ ,  $L = 1$ , and  $R = 0.125$ .
- In this case, it's the RMS voltage that is 0.25 volts
- This means that  $E(t) = 0.25\sqrt{2} \sin(t)$ , and  $E'(0) = 0.25\sqrt{2} \cos(t)$ , so that  $I$  is a solution to the initial value problem

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- As per our previous discussion, we write

$$I = I_{\text{transient}} + I_{\text{stable}},$$

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- Using the equation of the previous slide,

$$I_{\text{steady}} = r \cos(\omega t - \delta),$$

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$$I_{\text{transient}} = r_0 e^{-t/16} \cos\left(\frac{\sqrt{255}}{16}t - \delta_0\right),$$

- where  $r_0$  and  $\delta_0$  are some constants depending on our initial condition  $I(0) = 2$  and  $I'(0) = 0$ .
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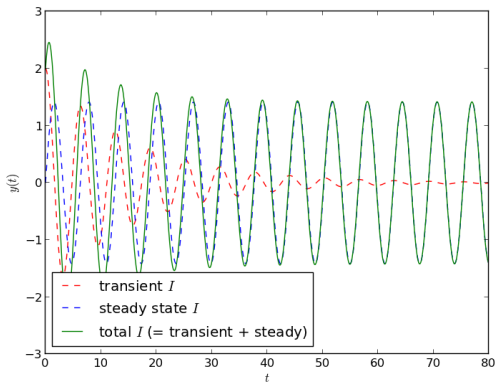
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Next time:

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