

# Math 309 Lecture 9

## Diagonalization and Jordan Normal Form

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# Today!

Plan for today:

- Diagonalization
- Jordan Normal Form
- Calculating a Fundamental Matrix

Next time:

- Nonhomogeneous Differential Equations

# Outline

- 1 Diagonalization
  - Basics
  - How to Diagonalize
- 2 Jordan Normal Form
  - Jordan Blocks
  - How to Find Jordan Decomposition
  - $2 \times 2$  Case

# Diagonalizable Matrices

- two matrices  $A$  and  $B$  are **similar** if there exists an invertible matrix  $P$  satisfying  $P^{-1}AP = B$
- natural concept – related to change of basis
- a matrix is said to be **diagonalizable** if it is similar to a diagonal matrix
- a matrix which is not diagonalizable is called **defective**

## Question

What matrices are diagonalizable?

# Eigenbasis

- we have the following theorem:

## Theorem

Let  $A$  be a diagonal matrix. Then the following are equivalent:

- (a)  $A$  is diagonalizable
- (b)  $\mathbb{C}^n$  as a basis consisting of eigenvectors of  $A$  (an **eigenbasis**)
- (c) for every eigenvalue  $\lambda$  of  $A$ , the algebraic and geometric multiplicity of  $\lambda$  are the same

- in other words,  $A$  needs “enough” eigenvectors

## Special cases

- there are a couple theorems that help us to decide right away if matrices are diagonalizable

### Theorem

If all of the eigenvalues of  $A$  have algebraic multiplicity 1, then  $A$  is diagonalizable

### Theorem (Spectral Theorem)

If  $A$  is **normal** (ie.  $A$  and  $A^\dagger$  commute), then  $A$  is diagonalizable

- in particular, **Hermitian** ( $A = A^\dagger$ ) and **unitary** ( $A^\dagger = A^{-1}$ ) matrices are diagonalizable

# Example

- the following matrix is diagonalizable (why?):

$$\begin{pmatrix} 3 & 2 & 1 \\ 2 & 5 & 4 \\ 1 & 4 & -1 \end{pmatrix}$$

- the following matrix is diagonalizable (why?):

$$\begin{pmatrix} 3 & 4 & 9 \\ 0 & 1 & -4 \\ 0 & 0 & -1 \end{pmatrix}$$

- the following matrix is NOT diagonalizable (why?):

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

# Use the Eigenbasis

## Question

How do we diagonalize a matrix?

- suppose that  $A$  is diagonalizable
- let  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$  be an eigenbasis for  $\mathbb{R}^n$
- let  $\lambda_1, \lambda_2, \dots, \lambda_n$  be the corresponding eigenvalues (resp)
- then  $P^{-1}AP = D$  for

$$P = ( \vec{v}_1 \quad \vec{v}_2 \quad \dots \quad \vec{v}_n ), \quad D = \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{pmatrix}$$

- order is important!!



# Example

## Question

Find  $P$  invertible and  $D$  diagonal so that  $P^{-1}AP = D$  for

$$A = \begin{pmatrix} 3 & 2 & 1 \\ 2 & 5 & 4 \\ 1 & 4 & -1 \end{pmatrix}$$

Steps:

- 1 Calculate the eigenvalues (diagonal values of matrix  $D$ )
- 2 For each eigenvalue, find a basis for the eigenspace
- 3 Put all the bases together to get an eigenbasis for  $\mathbb{R}^3$
- 4 Use them as column vectors in matrix  $P$

# Example

- 1 characteristic poly:

$$p_A(x) = \det(A - xI) = -(x + 3)(x - 2)(x - 8)$$

Therefore eigenvalues are  $-3, 2, 8$

- 2 corresponding eigenspaces:

$$E_{-3} = \text{span} \left\{ \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \right\}$$

$$E_2 = \text{span} \left\{ \begin{pmatrix} -5 \\ 2 \\ 1 \end{pmatrix} \right\}$$

$$E_8 = \text{span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} \right\}$$

# Example

③ eigenbasis for  $\mathbb{R}^3$ :

$$\left\{ \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} -5 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} \right\}$$

④ consequently we have

$$P = \begin{pmatrix} 0 & -5 & 1 \\ -1 & 2 & 2 \\ 1 & 1 & 1 \end{pmatrix} \quad D = \begin{pmatrix} -3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 8 \end{pmatrix}$$

# Basic Definition

- a **Jordan block** of size  $m$  is an  $m \times m$  matrix of the form

$$J_m(\lambda) := \begin{pmatrix} \lambda & 1 & 0 & 0 & \dots & 0 \\ 0 & \lambda & 1 & 0 & \dots & 0 \\ 0 & 0 & \lambda & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 \\ 0 & 0 & 0 & 0 & \dots & \lambda \end{pmatrix}$$

- ie. it is a matrix with some constant value  $\lambda$  on the main diagonal and 1 on the first superdiagonal

# Examples

- some examples of **Jordan blocks** include

$$J_1(13) = (13)$$

$$J_2(-7) = \begin{pmatrix} 7 & 1 \\ 0 & 7 \end{pmatrix}$$

$$J_3(-\sqrt{5}) = \begin{pmatrix} \sqrt{5} & 1 & 0 \\ 0 & \sqrt{5} & 1 \\ 0 & 0 & \sqrt{5} \end{pmatrix}$$

$$J_4(\pi) = \begin{pmatrix} \pi & 1 & 0 & 0 \\ 0 & \pi & 1 & 0 \\ 0 & 0 & \pi & 1 \\ 0 & 0 & 0 & \pi \end{pmatrix}$$

# Jordan Normal Form

- A matrix  $B$  is in **Jordan normal form** if it is in the form

$$B = \begin{pmatrix} J_{m_1}(\lambda_1) & 0 & \dots & 0 \\ 0 & J_{m_2}(\lambda_2) & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & J_{m_\ell}(\lambda_\ell) \end{pmatrix}$$

- for example, a diagonal matrix is a matrix in Jordan normal form
- other examples include

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix} \quad \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{pmatrix} \quad \begin{pmatrix} 3 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 7 & 1 \\ 0 & 0 & 0 & 7 \end{pmatrix}$$

# Jordan Decomposition

- not every matrix is diagonalizable
- however, *every* matrix is similar to a matrix in Jordan normal form
- the Jordan normal form of a matrix is unique (up to permutation of the Jordan blocks)
- one way to think about this is in terms of **generalized eigenvectors**
- a **generalized eigenvector of rank  $k$**  with eigenvalue  $\lambda$  is a nonzero vector in the kernel of  $(A - \lambda I)^k$  but not in the kernel of  $(A - \lambda I)^{k-1}$
- the dimension of the space of generalized eigenvectors of an eigenvalue is always the same as the algebraic multiplicity
- this gives rise to Jordan normal form

# How to Decompose

## Question

How do we find  $P, N$  so that  $P^{-1}AP = N$ , with  $N$  in Jordan normal form?

- difficult operation in general
- for each eigenvalue  $\lambda$ , find a basis  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_r$  of the eigenspace  $E_\lambda(A)$
- then find generalized eigenvectors...
- difficult/long to do in general
- will focus on  $2 \times 2$  and  $3 \times 3$  cases



# Possible $2 \times 2$ Jordan Normal Forms

## Question

If  $A$  is a  $2 \times 2$  matrix, what are the possible Jordan normal forms of  $A$ ?

- if  $A$  is nondegenerate, then  $A$  is diagonalizable with eigenvalues  $\lambda_1, \lambda_2$  and its Jordan form is

$$\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$$

- if  $A$  is degenerate, then  $A$  has exactly one eigenvalue  $\lambda$  with alg. mult 2, and geom. mult 1, and its Jordan form is

$$\begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}$$

# Calculating the matrix $P$

## Question

If  $A$  is a  $2 \times 2$  matrix, how do we find  $P$  so that  $P^{-1}AP = N$ ?

- if  $A$  is nondegenerate, with eigenvalues  $\lambda_1, \lambda_2$  we do the usual thing:

STEP 1: choose  $\vec{v}_1 \in E_{\lambda_1}(A)$

STEP 2: choose  $\vec{v}_2 \in E_{\lambda_2}(A)$

STEP 3: set  $P = [\vec{v}_1 \ \vec{v}_2]$

- if  $A$  is degenerate with eigenvalue  $\lambda$ , then use the following steps:

STEP 1: choose  $\vec{v} \notin E_{\lambda}(A)$

STEP 2: set  $\vec{u} = (A - \lambda I)\vec{v}$

STEP 3: set  $P = [\vec{u} \ \vec{v}]$  (order is important!!)

# Example 1

## Question

Find the Jordan normal form of the matrix

$$A = \begin{pmatrix} 1 & 1/2 \\ 0 & 1 \end{pmatrix}$$

- char. poly is  $(x - 1)^2$ , so eigenvalues are 1, 1
- eigenspace:

$$E_1(A) = \text{span}\{\vec{v}\} = \text{span}\left\{\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right\}$$

- degenerate! since alg mult  $\neq$  geom mult.
- Choose  $\vec{v} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \notin E_1(A)$ . Calculate  $\vec{u} = (A - 1I)\vec{v} = \begin{pmatrix} 1/2 \\ 0 \end{pmatrix}$
- then take  $P = [\vec{u} \ \vec{v}]$ .

# Example 1 Continued

## Question

Find the Jordan normal form of the matrix

$$A = \begin{pmatrix} 1 & 1/2 \\ 0 & 1 \end{pmatrix}$$

- in other words

$$P = \begin{pmatrix} 1/2 & 0 \\ 0 & 1 \end{pmatrix}$$

- then Jordan form for  $A$  is

$$N = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

- and we have  $P^{-1}AP = N$

## Example 2

### Question

Find the Jordan normal form of the matrix

$$A = \begin{pmatrix} 7 & 1 \\ -1 & 5 \end{pmatrix}$$

- char. poly is  $(x - 6)^2$ , so eigenvalues are 6, 6
- eigenspace:

$$E_6(A) = \text{span}\{\vec{v}\} = \text{span}\left\{\begin{pmatrix} 1 \\ -1 \end{pmatrix}\right\}$$

- degenerate! since alg mult  $\neq$  geom mult.
- Choose  $\vec{v} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \notin E_6(A)$ . Calculate  $\vec{u} = (A - 6I)\vec{v} = \begin{pmatrix} 7 \\ -1 \end{pmatrix}$ .
- then take  $P = [\vec{u} \ \vec{v}]$ .

## Example 2

### Question

Find the Jordan normal form of the matrix

$$A = \begin{pmatrix} 7 & 1 \\ -1 & 5 \end{pmatrix}$$

- in other words

$$P = \begin{pmatrix} 7 & -1 \\ 1 & 0 \end{pmatrix}$$

- then Jordan form for  $A$  is

$$N = \begin{pmatrix} 6 & 1 \\ 0 & 6 \end{pmatrix}$$

- and we have  $P^{-1}AP = N$

# summary!

what we did today:

- diagonalizable matrices
- jordan normal form

plan for next time:

- $3 \times 3$  Jordan normal form
- calculating a fundamental matrix
- nonhomogeneous equations