

# Math 309 Lecture 1

## Linear Algebraic Systems and Eigenstuff

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# Today!

Plan for today:

- Systems of Linear Algebraic Equations
- Linear Independence
- Eigenvectors and Eigenvalues

Next time:

- More on Eigenvectors and Eigenvalues

# Outline

- 1 Linear Algebraic Systems
  - Linear Systems
  - Solving Linear Algebraic Systems
- 2 Linear Dependence
  - Basic Definition
  - How to Check Linear Independence
- 3 Eigenvectors and Eigenvalues

# Algebraic Systems of Equations

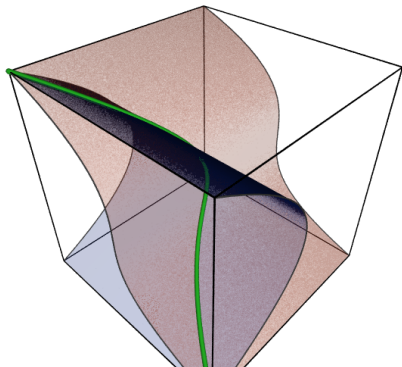
- An algebraic system of equations is something of the form

$$\begin{cases} F_1(x_1, x_2, \dots, x_n) = 0 \\ F_2(x_1, x_2, \dots, x_n) = 0 \\ \vdots = \vdots \\ F_m(x_1, x_2, \dots, x_n) = 0 \end{cases}$$

- $x_1, \dots, x_n$  are **variables**
- $F_1, \dots, F_m$  are functions describing relationships between variables
- **solutions** are values of  $x_1, \dots, x_n$  satisfying relationships

# Algebraic System Example

**Figure:** Graph of solutions to the system



- For example

$$\begin{cases} xz - y^2 = 0 \\ y - z^2 = 0 \end{cases}$$

- Solution is **green** curve
- Made from intersection of surfaces
- **Never forget!** solutions to algebraic systems have **both** *algebraic* and *geometric* meaning

# Linear Algebraic Systems

- An algebraic system is **linear** if it is of the form

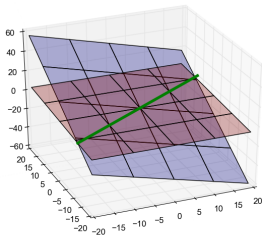
$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n - b_1 & = 0 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n - b_2 & = 0 \\ & \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n - b_m & = 0 \end{cases}$$

- for some constants  $a_{ij}$  and  $b_i$
- in terms of matrices:  $A\vec{x} = \vec{b}$

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix}, \vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}, \vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

# Linear Algebraic System Example

**Figure:** Graph of solutions to the system



- For example

$$\begin{cases} 2y - 8z = 0 \\ x - 2y + z = 0 \end{cases}$$

- Matrix version:

$$\begin{pmatrix} 0 & 2 & -8 \\ 1 & -2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

- Solution is **green** curve
- Made from intersection of planes
- linear equations make **straight** things

# Solving Linear Systems

## Question

How can we algebraically solve a linear system?

- we can use **Gaussian elimination**
- given a linear system  $A\vec{x} = \vec{b}$  as above
- form augmented matrix  $[A|\vec{b}]$ :

$$[A|\vec{b}] = \left( \begin{array}{cccc|c} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & b_m \end{array} \right)$$

- We perform **elementary row operations** to put  $[A|\vec{b}]$  in **row reduced echelon form (RREF)**



# Example Solution 1

- consider the previous example linear system

$$\begin{pmatrix} 0 & 2 & -8 \\ 1 & -2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

- the augmented matrix is

$$\left( \begin{array}{ccc|c} 0 & 2 & 8 & 0 \\ 1 & 2 & 1 & 0 \end{array} \right)$$

- row reduce

$$\xrightarrow{R_1 \leftrightarrow R_2} \left( \begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & 2 & 8 & 0 \end{array} \right) \xrightarrow{R_1 - R_2} \left( \begin{array}{ccc|c} 1 & 0 & -7 & 0 \\ 0 & 2 & 8 & 0 \end{array} \right) \xrightarrow{R_2/2} \left( \begin{array}{ccc|c} 1 & 0 & -7 & 0 \\ 0 & 1 & 4 & 0 \end{array} \right)$$

## Example Solution 1

- how do we interpret RREF?

$$\left( \begin{array}{ccc|c} 1 & 0 & -7 & 0 \\ 0 & 1 & 4 & 0 \end{array} \right)$$

- first nonzero entry of a row is a **pivot** – corresponding column is a **pivot column**
- pivot columns correspond to **dependent variables**
- other columns correspond to **free variables**
- express dependent variables in terms of free variables
- row 1 says  $x - 7z = 0$
- row 2 says  $y + 4z = 0$
- solution is

$$x = 7z, \quad y = -4z.$$

## Example Solution 1

- consider the linear system

$$\begin{pmatrix} 2 & 6 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \end{pmatrix}$$

- the augmented matrix is

$$\left( \begin{array}{cc|c} 2 & 6 & 2 \\ 3 & -1 & -2 \end{array} \right)$$

- row reduce

$$\begin{aligned} &\xrightarrow{R_1/2} \left( \begin{array}{cc|c} 1 & 2 & 1 \\ 3 & -1 & -2 \end{array} \right) \xrightarrow{R_2-3R_1} \left( \begin{array}{cc|c} 1 & 2 & 1 \\ 0 & -7 & -5 \end{array} \right) \\ &\xrightarrow{R_2/(-7)} \left( \begin{array}{cc|c} 1 & 2 & 1 \\ 0 & 1 & 5/7 \end{array} \right) \xrightarrow{R_1-2R_2} \left( \begin{array}{cc|c} 1 & 0 & -3/7 \\ 0 & 1 & 5/7 \end{array} \right) \end{aligned}$$

- solution is  $x = -3/7$ ,  $y = 5/7$

# Vectors

- (column) **vectors** are  $m \times 1$  matrices
- vectors describe things with magnitude and direction
- like matrices, we can add vectors and multiply vectors by scalars
- we *cannot* multiply vectors (shapes are not compatible)
- given vectors  $\vec{v}_1, \dots, \vec{v}_n$  we can make a new vector by taking a **linear combination**:

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$$

# Linear Independence

- a set of vectors  $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$  is called **linearly dependent** if there exist constants  $c_1, \dots, c_n$  not all zero, so that

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$$

- a set of vectors  $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$  is called **linearly independent** if the only linear combination satisfying

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$$

is the **trivial** linear combination  $c_1 = 0, c_2 = 0, \dots, c_n = 0$ .

# Linear Independence Example

- Given vectors

$$\vec{v}_1 = \begin{pmatrix} 1 \\ 4 \\ 7 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} 2 \\ 5 \\ 8 \end{pmatrix}, \vec{v}_3 = \begin{pmatrix} 3 \\ 6 \\ 9 \end{pmatrix}$$

- is  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  linearly independent?
- no, since

$$-1 \begin{pmatrix} 1 \\ 4 \\ 7 \end{pmatrix} + 2 \begin{pmatrix} 2 \\ 5 \\ 8 \end{pmatrix} + -1 \begin{pmatrix} 3 \\ 6 \\ 9 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

# Linear Independence Example

- Given vectors

$$\vec{v}_1 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \vec{v}_3 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

- is  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  linearly independent?
- yes (we will show this in a second)

# Checking Linear Independence

## Question

How do we tell if a set of vectors  $\{\vec{v}_1, \dots, \vec{v}_n\}$  is linearly independent?

- we are trying to decide if there exist  $c_1, \dots, c_n$  such that

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$$

- in terms of matrices, trying to solve  $V\vec{c} = \vec{0}$  for

$$V = (\vec{v}_1 \ \vec{v}_2 \ \dots \ \vec{v}_n), \quad \vec{c} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}$$



# Checking Linear Independence Example

- consider the vectors

$$\vec{v}_1 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \vec{v}_3 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

- $c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 = \vec{0}$  gives:

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

- the augmented matrix is

$$\left( \begin{array}{ccc|c} 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 \end{array} \right)$$

# Checking Linear Independence Example

- we row reduce

$$\xrightarrow{R_1 \leftrightarrow R_2} \left( \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 1 & 0 & 0 \end{array} \right) \xrightarrow{R_3 - R_1} \left( \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & -1 & 0 \end{array} \right) \xrightarrow{R_3 - R_2} \left( \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & -2 & 0 \end{array} \right)$$

$$\xrightarrow{R_3 / (-2)} \left( \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right) \xrightarrow{R_1 - R_3} \left( \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right) \xrightarrow{R_2 - R_3} \left( \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right)$$

- therefore the *only* solution is  $c_1 = 0, c_2 = 0, c_3 = 0$
- this means that  $\vec{v}_1, \vec{v}_2, \vec{v}_3$  are linearly independent

## Checking Linear Independence

- recall that the **rank** of a matrix  $A$  is the number of **pivot columns** in its RREF
- to decide linear independence, the following theorem is helpful:

### Theorem

The set of vectors

$$\{\vec{v}_1, \dots, \vec{v}_n\}$$

is linearly independent if and only if the associated matrix  $V = (\vec{v}_1 \ \vec{v}_2 \ \vec{v}_n)$  has rank  $n$

- therefore we can check for linear dependence by calculating the rank of the corresponding matrix

# What are Eigenvectors?

**Figure:** *eigen* is German for *proper*



- Let  $A$  be an  $n \times n$  matrix
- An **eigenvector**  $\vec{v}$  of  $A$  with **eigenvalue**  $\lambda$  is a *nonzero* vector  $\vec{v}$  satisfying

$$A\vec{v} = \lambda\vec{v}$$

- For example  $\vec{v} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  is an eigenvector of  $A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$  with eigenvalue 2

# Finding Eigenvalues

## Question

How can we figure out what eigenvalues a matrix has?

- look at the **characteristic polynomial**

$$p_A(x) = \det(A - xI)$$

- eigenvalues of  $A$  are roots of the characteristic polynomial
- for example, consider:

$$A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

- $p_A(x) = \det(A - xI) = x^2 - 2x$
- eigenvalues are 0 and 2

# Finding Eigenvectors

## Question

How can we figure out what eigenvectors a matrix has?

- given eigenvalue  $\lambda$ , solve the system  $A\vec{v} = \lambda\vec{v}$
- equivalently, solve the system  $(A - \lambda I)\vec{v} = \vec{0}$
- Note: the solutions to  $(A - \lambda I)\vec{v} = \vec{0}$  form a **vector space**, called the **eigenspace** of  $A$  for  $\lambda$
- denoted  $E_\lambda(A)$

## Finding Eigenvectors

- for example, consider:

$$A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

- the eigenvalues are again 0, 2
- the eigenspaces are obtained by solving  $A\vec{v} = \vec{0}$  and  $(A - 2I)\vec{v} = \vec{0}$
- this gives

$$E_0(A) = \left\{ \begin{pmatrix} x \\ -x \end{pmatrix} : x \in \mathbb{C} \right\}$$

$$E_2(A) = \left\{ \begin{pmatrix} x \\ x \end{pmatrix} : x \in \mathbb{C} \right\}$$

# Summary!

What we did today:

- Systems of Linear Algebraic Equations
- Linear Independence
- Eigenvectors and Eigenvalues

Plan for next time:

- More on eigenvectors and eigenvalues
- More linear algebra stuff in general